

Information Retrieval

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Lecture 8, Wednesday December 8th, 2015
(Vector Space Model, Latent Semantic Indexing)

Prof. Dr. Hannah Bast
Chair of Algorithms and Data Structures
Department of Computer Science
University of Freiburg

Overview of this lecture

■ Organizational

- Your experiences with ES7 cookies, UTF-8

■ Contents

- Synonyms motivation + examples
- Vector Space Model (VSM) documents as vectors
- Latent Semantic Indexing (LSI) find synonyms automatically
- Using LSI for retrieval three variants + another
- Exercise Sheet 8: re-implement your code from ES2 using the VSM, and re-evaluate benchmark from ES2 using LSI

■ Summary / excerpts

- "This exercise sheet was annoying"

Sorry ... but a perfect summary of the typical developer experience with encoding issues, in particular UTF-8

- "Very useful ... I will not struggle anymore with encodings"

Thanks, that was exactly the intention of the lecture !

- Quite some bit fiddling needed

Some were not up to the low-level details and defaulted to the built-in functions

■ Motivation

- We have already seen fuzzy (prefix) search

Search **uniwercity** find **university**

- Today we want to find synonyms = others word meaning the same thing as a given word

Search **university** find **college**

Search **bringdienst** find **lieferservice**

Search **cookie** find **biscuit**

Note: typically no **lexical** similarity whatsoever, the similarity is only in the **meaning**

■ Solution 1: Maintain a thesaurus

- For each word, manually compile a list of synonyms

university: uni, academy, college, ...

bringdienst:ieferservice, heimservice, pizzaservice, ...

cookie: biscuit, confection, wafer, ...

- Problem 1: laborious, and still notoriously out of date
- Problem 2: it depends on the context, which synonyms are appropriate ... for example:

university award \neq academy award

http cookie \neq http biscuit

■ Solution 2: Track user behavior

- Investigate whole **search sessions**

Track sessions with, guess what: COOKIES

- For example, many users searching for either of

pizza freiburg

bringdienst freiburg

then click on

Lieferservice Freiburg im Breisgau

This provides a hint that pizza and bringdienst and
lieferservice are related

■ Solution 3: Automatic methods

- The text itself also tells us which words are related
- For example, consider (German) **delivery webpages**

some mention **Bringdienst**, others say **Lieferservice**

but apart from that they use the same words a lot, like:
pizza, mozzarella, käse, nudeln, vegetarisch, ...

Can we find out (automatically) that two words are related, based on the similar context they appear in ?

This is the topic of today's lecture !

Vector Space Model 1/8

■ Motivation

- For this lecture, it will be useful to represent documents as **vectors** ... here is our running example for today:

	D ₁	D ₂	D ₃	D ₄	D ₅	D ₆
internet	1	1	0	1	0	0
web	1	0	1	1	0	0
surfing	1	1	1	2	1	1
beach	0	0	0	1	1	1

- Each row corresponds to a word, each column to a document
- Non-zero entries: score for that word in that document

In the lecture, we use tf scores ... for ES8, use BM25 scores

■ Terminology

- Often referred to as the **Vector Space Model (VSM)**
- In the VSM, words are traditionally referred to as **terms**
- Putting the vectors from all documents from a given corpus side by side gives us the so-called **term-document matrix**

	D₁	D₂	D₃	D₄	D₅	D₆
internet	1	1	0	1	0	0
web	1	0	1	1	0	0
surfing	1	1	1	2	1	1
beach	0	0	0	1	1	1

Vector Space Model 3/8

■ Retrieval

- A query can also be represented as a vector ... we take **1** for a term used in the query, and **0** for all other terms
- We measure the relevance of a document to the query by taking the **dot product** of the two vectors

Note: this is exactly the same score as in Lecture 2

	D ₁	D ₂	D ₃	D ₄	D ₅	D ₆	Q
internet	1	1	0	1	0	0	0
web	1	0	1	1	0	0	1
surfing	1	1	1	2	1	1	1
beach	0	0	0	1	1	1	0
	2	1	2	3	1	1	

Vector Space Model 4/8

■ Algebra

- More formally, let us write A for the term-document matrix and q for the query vector
- Then the matrix-vector product $q^T \cdot A$ gives us a vector with the relevance scores of all the documents

Let us implement this together now

A

	D_1	D_2	D_3	D_4	D_5	D_6	Q
internet	1	1	0	1	0	0	0
web	1	0	1	1	0	0	1
surfing	1	1	1	2	1	1	1
beach	0	0	0	1	1	1	0

q^T

■ Basic linear algebra in Python

- For standard linear algebra, we can use **numpy**

```
sudo apt-get install python3-numpy
```

```
import numpy
```

```
A = numpy.array([[1, 1, 0, 1, 0, 0], ...])
```

```
q = numpy.array([0, 1, 1, 0])
```

```
scores = q.dot(A)
```

```
print(scores)
```

Use **numpy.array** and **dot** for multiplication, not *****

q is a row vector above = q^T from the previous slide

See the code from the lecture for more example usage

■ Sparse matrices

- Most entries in a term-document matrix are **zero**

Storing all entries explicitly infeasible for large matrices

- Sparse-matrix representation: store only the non-zero entries (together with their row and column index)

$(1, 0, 0), (1, 0, 1), (1, 0, 3), \dots, (2, 2, 3), \dots$

value *row* *column*

	0	1	2	3	4	5	
	D ₁	D ₂	D ₃	D ₄	D ₅	D ₆	
internet	<u>1</u>	1	0	1	0	0	0
web	1	0	1	1	0	0	1
surfing	1	1	1	<u>2</u>	1	1	2
beach	0	0	0	1	1	1	3

■ Sparse matrices

- Two principle ways to store the list of non-zero values

row-major: store row by row (sort by row index first)

column-major: store col by col (sort by col index first)

- Note: the sparse row-major representation of a term-document matrix is equivalent to an inverted index

(1, 0, 0), (1, 0, 1), (1, 0, 3) inverted list for term 0

(1, 1, 0), (1, 1, 2), (1, 1, 3) inverted list for term 1

(1, 2, 0), (1, 2, 1), (1, 2, 1), ... inverted list for term 2

(1, 3, 3), (1, 3, 4), (1, 3, 5) inverted list for term 3

(non-zero score, row index = term id, col index = doc id)

Vector Space Model 8/8

CSR = compressed
sparse
row

■ Sparse matrices in Python

- Not included in numpy, we have to use **scipy**

```
sudo apt-get install python3-scipy
```

```
import scipy.sparse
```

```
nz_vals = [1, 1, 1, 1, 1, 1, ...]
```

```
row_inds = [0, 0, 0, 1, 1, 1, ...]
```

```
col_inds = [0, 1, 3, 0, 2, 3, ...]
```

```
A = scipy.sparse.csr_matrix((nz_vals, (row_inds, col_inds)))
```

```
q = scipy.sparse.csr_matrix([0, 1, 1, 0])
```

```
scores = q.dot(A)
```

```
print(scores)
```

See the code from the lecture for more example usage

■ Motivation

- Let's look at our example again:

D_1 and D_2 and D_3 are "about" surfing the web

D_5 and D_6 are "about" surfing on the beach

internet and web are **synonyms**, surfing is a **polysem**
= means different things in different context

	D_1	D_2	D_3	D_4	D_5	D_6
internet	1	1	0	1	0	0
web	1	0	1	1	0	0
surfing	1	1	1	2	1	1
beach	0	0	0	1	1	1

■ Motivation

- Let's look at the query **web surfing** again, using dot-product similarity as explained on slide 10
- Then $\text{sim}(D_3, Q) > \text{sim}(D_2, Q) = \text{sim}(D_5, Q)$

But D_2 seems just as relevant for the query as D_3 , only that the word "internet" is used instead of "web"

	<i>REL</i> D_1	<i>REL</i> D_2	<i>REL</i> D_3	<i>REL</i> D_4	D_5	D_6	Q
internet	1	1	0	1	0	0	0
web	1	0	1	1	0	0	1
surfing	1	1	1	2	1	1	1
beach	0	0	0	1	1	1	0
	2	1	2	3	1	1	

Latent Semantic Indexing 3/9

■ Conceptual solution

	^{REL} D ₁	^{REL} D ₂	^{REL} D ₃	^{REL} D ₄	[×] D ₅	[×] D ₆	Q
internet	1	1	1	1	0	0	0
web	1	1	1	1	0	0	1
surfing	1	1	1	2	1	1	1
beach	0	0	0	1	1	1	0
	²	²	²	³	¹	¹	

Add the missing synonyms to the documents

Then indeed: $\text{sim}(D_1, Q) = \text{sim}(D_2, Q) = \text{sim}(D_3, Q)$

The goal of LSI is to do something like this automatically

Latent Semantic Indexing 4/9

- A simple but powerful observation

	$=B_1$ D₁	$=B_1$ D₂	$=B_1$ D₃	$=B_1+B_2$ D₄	$=B_2$ D₅	$=B_2$ D₆	B₁	B₂
internet	1	1	1	1	0	0	1	0
web	1	1	1	1	0	0	1	0
surfing	1	1	1	2	1	1	1	1
beach	0	0	0	1	1	1	0	1

The modified matrix has **column rank 2**

That is, we can write each column as a (different) linear combination of the same two base columns (B_1 and B_2)

Note 1: the original matrix had column rank 4

Note 2: one can prove that **column rank = row rank**

■ Matrix factorization

$$\begin{array}{c}
 \begin{array}{c} 0 \quad 1 \quad 2 \quad \color{red}{3} \quad 4 \quad 5 \\ \text{0} \\ \text{1} \\ \color{red}{2} \\ \text{3} \end{array}
 \begin{array}{|c|c|c|c|c|c|}
 \hline D_1 & D_2 & D_3 & D_4 & D_5 & D_6 \\
 \hline
 \begin{array}{c} 1 \\ 1 \\ 1 \\ 0 \end{array} &
 \begin{array}{c} 1 \\ \color{blue}{1} \\ 1 \\ 0 \end{array} &
 \begin{array}{c} \color{blue}{1} \\ 1 \\ 1 \\ 0 \end{array} &
 \begin{array}{c} 1 \\ 1 \\ \color{red}{2} \\ 1 \end{array} &
 \begin{array}{c} 0 \\ 0 \\ 1 \\ 1 \end{array} &
 \begin{array}{c} 0 \\ 0 \\ 1 \\ 1 \end{array} \\
 \hline
 \end{array}
 \begin{array}{c} 4 \times 6 \end{array}
 \end{array}
 =
 \begin{array}{c}
 \begin{array}{c} \text{0} \\ \text{1} \\ \color{red}{2} \\ \text{3} \end{array}
 \begin{array}{|c|c|}
 \hline B_1 & B_2 \\
 \hline
 \begin{array}{c} 1 \\ 1 \\ \color{red}{1} \\ 0 \end{array} &
 \begin{array}{c} 0 \\ 0 \\ \color{red}{1} \\ 1 \end{array} \\
 \hline
 \end{array}
 \begin{array}{c} 4 \times 2 \end{array}
 \cdot
 \begin{array}{c}
 \begin{array}{c} \text{0} \quad 1 \quad 2 \quad \color{red}{3} \quad 4 \quad 5 \\ \text{0} \\ \text{1} \\ \text{2} \end{array}
 \begin{array}{|c|c|c|c|c|c|}
 \hline D'_1 & D'_2 & D'_3 & D'_4 & D'_5 & D'_6 \\
 \hline
 \begin{array}{c} 1 \\ 1 \\ 0 \end{array} &
 \begin{array}{c} 1 \\ 1 \\ 0 \end{array} &
 \begin{array}{c} 1 \\ 1 \\ 0 \end{array} &
 \begin{array}{c} \color{red}{1} \\ \color{red}{1} \\ \color{red}{1} \end{array} &
 \begin{array}{c} 0 \\ 0 \\ 1 \end{array} &
 \begin{array}{c} 0 \\ 0 \\ 1 \end{array} \\
 \hline
 \end{array}
 \begin{array}{c} 2 \times 6 \\ B_1 \quad B_1 \quad B_1 \quad B_1+B_2 \quad B_2 \quad B_2 \end{array}
 \end{array}$$

Equivalently: the 4×6 term-document matrix can be written as a product of a 4×2 matrix with a 2×6 matrix

The base vectors B_1 and B_2 are the underlying "**concepts**"

The vectors D'_1, \dots, D'_6 are the representation of the documents in the (lower-dimensional) "**concept space**"

■ The goal of LSI

- Given an $m \times n$ term-document matrix A and $k < \text{rank}(A)$
- Then find a matrix A' of (column) rank k such that the difference between A' and A is **as small as possible**

Formally: $A' = \text{argmin}_{A' \text{ } m \times n \text{ with rank } k} \|A - A'\|$

For the $\| \dots \|$ we take the so-called **Frobenius-norm**

This is defined as $\|D\| := \sqrt{\sum_{ij} D_{ij}^2}$

The reason for using this norm is purely technical: that way, the math on the next slides works out nicely

■ How to find / compute such an A'

- We first compute the so-called **singular value decomposition (SVD)** of the given matrix A :

Theorem: for any $m \times n$ matrix A of rank r , there exist U, S, V such that $A = U \cdot S \cdot V$, and where

U is an $m \times r$ matrix with $U \cdot U^T = I_m$ the $m \times m$ identity matrix

S is a $r \times r$ matrix with entries only on its diagonal

V is an $r \times n$ matrix with $V^T \cdot V = I_n$ the $n \times n$ identify matrix

The decomposition is unique up to simultaneous permutation of the rows/columns of U, S , and V

Standard form: diagonal entries of S positive and sorted

■ Using the SVD our task becomes easy

– Let $A = U \cdot S \cdot V$ be the SVD of A

– For a given $k < \text{rank}(A)$ let

U_k = the first k columns of U now an $m \times k$ matrix

S_k = the upper $k \times k$ part of S now a $k \times k$ matrix

V_k = the first k rows of V now a $k \times n$ matrix

Note: then still $U_k \cdot U_k^T = I_m$ and $V_k \cdot V_k^T = I_n$

Let $A_k = U_k \cdot S_k \cdot V_k^T$

Then A_k is a matrix of rank k that minimizes $\|A - A_k\|$

$$(A \cdot A^T)^T = A^{TT} \cdot A^T = A \cdot A^T$$

■ How to compute the SVD

- Easy to compute from the **Eigenvector decomposition**

Namely of the quadratic matrices $A \cdot A^T$ and $A^T \cdot A$

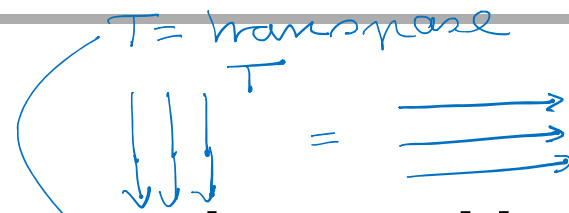
- In practice, the more direct **Lanczos** method is used

This has complexity $O(k \cdot \text{nnz})$, where k is the rank and nnz is the number of non-zero values in the matrix

Note that for term-document matrices $\text{nnz} \ll n \cdot m$

For ES8, just use **svds** from **scipy.sparse.linalg**

See the code from the lecture for a usage example



Using LSI for better Retrieval 1/8

- **Variant 1:** work with A_k instead of A

	D_1	D_2	D_3	D_4	D_5	D_6
internet	1	1	0	1	0	0
web	1	0	1	1	0	0
surfing	1	1	1	2	1	1
beach	0	0	0	1	1	1

D'_1	D'_2	D'_3	D'_4	D'_5	D'_6
0.9	0.6	0.6	1.0	0.0	0.0
0.9	0.6	0.6	1.0	0.0	0.0
1.1	0.9	0.9	2.1	1.0	1.0
-0.1	0.1	0.1	0.9	1.0	1.0

Our example A from the beginning

best rank-2 approximation A_2

Using LSI for better Retrieval 2/8

■ **Variant 1:** work with A_k instead of A

- Problem: A_k is a dense matrix, that is, most / all of it's $m \cdot n$ entries will be non-zero

Typically, both m and n will be very large, and then already storing this matrix is infeasible

E.g. if $m = 1000$ and $n = 10M \rightarrow m \cdot n = \mathbf{10\ G}$

Using LSI for better Retrieval 3/8

■ **Variant 2:** work with V_k instead of with A

- Recall: V_k gives the representation of the documents in the k -dimensional concept space

	D_1	D_2	D_3	D_4	D_5	D_6
internet	1	1	0	1	0	0
web	1	0	1	1	0	0
surfing	1	1	1	2	1	1
beach	0	0	0	1	1	1

Our example A from the beginning

D'_1	D'_2	D'_3	D'_4	D'_5	D'_6
0.4	0.3	0.3	0.7	0.3	0.3
0.5	0.2	0.2	0.0	-0.6	-0.6

V_2 from the SVD of A

Using LSI for better Retrieval 4/8

■ **Variant 2:** work with V_k instead of with A

- Observation: V_k is a dense matrix, that is, most or all of its $k \cdot n$ entries are non-zero

Note: the original matrix A has $m' \cdot n$ non-zero entries, where m' is the average number of words in a document

So storing V_k instead of A is ok if $k \approx m'$ or smaller

Note: no need for a sparse representation / an inverted index when storing / using V_k

This is the variant you should use for ES8.3

Using LSI for better Retrieval 5/8

■ **Variant 2:** work with \mathbf{V}_k instead of with \mathbf{A}

- Problem 2: we need to map the query to concept space

The dot-product similarity of query \mathbf{q} with all documents is

$$\mathbf{q}^T \cdot \mathbf{A}_k = \mathbf{q}^T \cdot (\mathbf{U}_k \cdot \mathbf{S}_k \cdot \mathbf{V}_k) = (\mathbf{q}^T \cdot \mathbf{U}_k \cdot \mathbf{S}_k) \cdot \mathbf{V}_k$$

Then $\mathbf{q}_k^T := \mathbf{q}^T \cdot \mathbf{U}_k \cdot \mathbf{S}_k$ is query mapped to concept space

- The dot product $\mathbf{q}_k^T \cdot \mathbf{V}_k$ requires time $\sim n \cdot k \dots$ since both \mathbf{q}_k and \mathbf{V}_k are dense

In comparison: computing the similarities of \mathbf{q} with the original documents requires time $O(n \cdot \#q)$ and less

where $\#q$ = number of query words in \mathbf{q}

Using LSI for better Retrieval 6/8

■ Variant 3: expand the original documents *column-orthogonal*

- In Variant 2, we have transformed both the query and the documents to concept space
- LSI can also be viewed as doing **document expansion** in the original space + no change in the query

Namely, let $T_k = U_k \cdot U_k^T$ this is an $m \times m$ matrix

Then one can easily prove that $A_k = T_k \cdot A$ *$r = \text{rank}(A)$*

$$\begin{aligned} T_2 \cdot A &= \underbrace{U_2 \cdot U_2^T \cdot U}_{\substack{m \times m \quad m \times m \quad m \times r}} \cdot \underbrace{S \cdot V}_{\substack{r \times r \quad r \times m}} = U_2 \cdot \underbrace{([I_r \ 0] \cdot S \cdot V)}_{= S_2 \cdot V_2} \\ &= \underbrace{[I_r \ 0]}_{r \times r} \cdot S \cdot V = A_2 \end{aligned}$$

For ES8, simply compute T_k from U_k as shown, then compute the 50 term pairs with the largest entries in T_k

Using LSI for better Retrieval 7/8

■ Variant 3: expand the original documents

- Here is some intuition for T_k , assuming 0 or 1 entries

In practice, we can get 0-1 entries by setting all entries in T above a certain threshold to 1, and all others to 0

says that "web" and "internet" are related

"add" web to D_i if internet is present

	internet	web	surfing	beach
0 internet	1	1	0	0
1 web	1	1	0	0
2 surfing	0	0	1	0
3 beach	0	0	0	1
	0	1	2	3

	D_i	D'_i
0	1	1
1	0	1
2	1	1
3	0	0

•

■ Linear combination with original scores

- Experience: LSI adds some useful information to the term-document matrix, but also a lot of **noise**
- In practice, one therefore uses a linear combination of the original scores and the LSI scores

Variant 1: $\text{scores} = \lambda \cdot q^T \cdot A + (1 - \lambda) \cdot q^T \cdot A_k$

Variant 2: $\text{scores} = \lambda \cdot q^T \cdot A + (1 - \lambda) \cdot q_k^T \cdot V_k$

Variant 3: $\text{scores} = \lambda \cdot q^T \cdot A + (1 - \lambda) \cdot q^T \cdot T_k \cdot A$

For ES9, take Variant 2 and experiment with a good λ

References

■ Further reading

- Textbook Chapter 18: Matrix decompositions & LSI
<http://nlp.stanford.edu/IR-book/pdf/18lsi.pdf>
- Deerwester, Dumais, Landauer, Furnas, Harshman
[Indexing by Latent Semantic Analysis](#), JASIS 41(6), 1990

■ Web resources

- http://en.wikipedia.org/wiki/Latent_semantic_indexing
- http://en.wikipedia.org/wiki/Singular_value_decomposition
- <http://www.numpy.org/>
- <http://www.scipy.org/>